

# NAG Toolbox for MATLAB

## s18af

### 1 Purpose

s18af returns a value for the modified Bessel Function  $I_1(x)$ , via the function name.

### 2 Syntax

```
[result, ifail] = s18af(x)
```

### 3 Description

s18af evaluates an approximation to the modified Bessel Function of the first kind  $I_1(x)$ .

**Note:**  $I_1(-x) = -I_1(x)$ , so the approximation need only consider  $x \geq 0$ .

The function is based on three Chebyshev expansions:

For  $0 < x \leq 4$ ,

$$I_1(x) = x \sum_{r=0}^{\prime} a_r T_r(t), \quad \text{where } t = 2\left(\frac{x}{4}\right)^2 - 1;$$

For  $4 < x \leq 12$ ,

$$I_1(x) = e^x \sum_{r=0}^{\prime} b_r T_r(t), \quad \text{where } t = \frac{x-8}{4};$$

For  $x > 12$ ,

$$I_1(x) = \frac{e^x}{\sqrt{x}} \sum_{r=0}^{\prime} c_r T_r(t), \quad \text{where } t = 2\left(\frac{12}{x}\right) - 1.$$

For small  $x$ ,  $I_1(x) \simeq x$ . This approximation is used when  $x$  is sufficiently small for the result to be correct to *machine precision*.

For large  $x$ , the function must fail because  $I_1(x)$  cannot be represented without overflow.

### 4 References

Abramowitz M and Stegun I A 1972 *Handbook of Mathematical Functions* (3rd Edition) Dover Publications

### 5 Parameters

#### 5.1 Compulsory Input Parameters

1: **x – double scalar**

The argument  $x$  of the function.

#### 5.2 Optional Input Parameters

None.

#### 5.3 Input Parameters Omitted from the MATLAB Interface

None.

## 5.4 Output Parameters

1: **result** – double scalar

The result of the function.

2: **ifail** – int32 scalar

0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**ifail** = 1

$x$  is too large. On soft failure the function returns the approximate value of  $I_1(x)$  at the nearest valid argument.

## 7 Accuracy

Let  $\delta$  and  $\epsilon$  be the relative errors in the argument and result respectively.

If  $\delta$  is somewhat larger than the *machine precision* (i.e., if  $\delta$  is due to data errors etc.), then  $\epsilon$  and  $\delta$  are approximately related by:

$$\epsilon \simeq \left| \frac{xI_0(x) - I_1(x)}{I_1(x)} \right| \delta.$$

Figure 1 shows the behaviour of the error amplification factor

$$\left| \frac{xI_0(x) - I_1(x)}{I_1(x)} \right|.$$

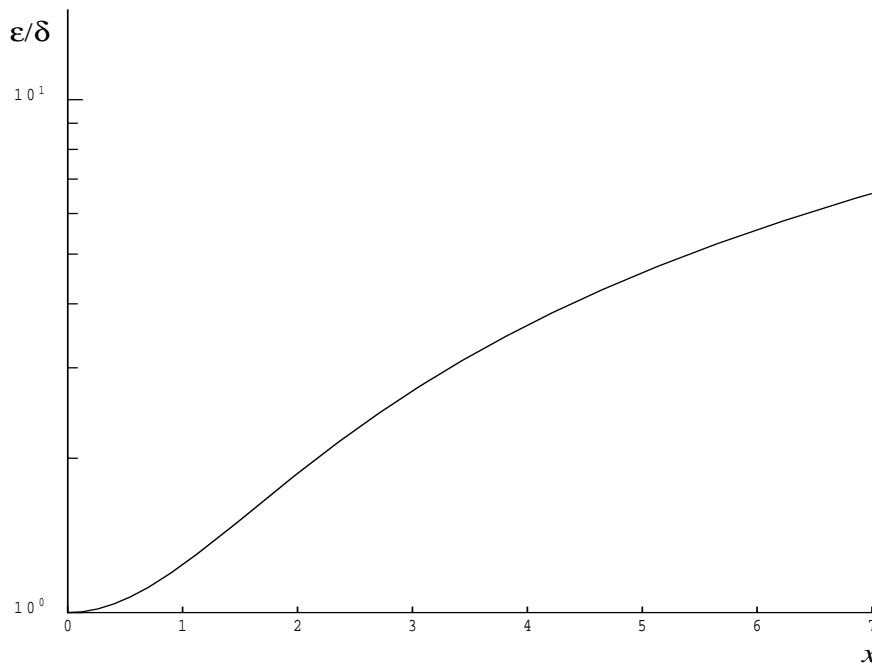


Figure 1

However, if  $\delta$  is of the same order as *machine precision*, then rounding errors could make  $\epsilon$  slightly larger than the above relation predicts.

For small  $x$ ,  $\epsilon \simeq \delta$  and there is no amplification of errors.

For large  $x$ ,  $\epsilon \simeq x\delta$  and we have strong amplification of errors. However the function must fail for quite moderate values of  $x$  because  $I_1(x)$  would overflow; hence in practice the loss of accuracy for large  $x$  is not excessive. Note that for large  $x$ , the errors will be dominated by those of the standard function EXP.

## 8 Further Comments

None.

## 9 Example

```
x = 0;
[result, ifail] = s18af(x)

result =
      0
ifail =
      0
```